Computational Phonology – Part II: Grammars, Learning, and the Future
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Abstract
Computational phonology studies sound patterns in the world’s languages from a computational perspective. This article shows that the similarities between different generative theories outweigh the differences, and discusses stochastic grammars and learning models within phonology from a computational perspective. Also, it shows how the hypothesis that all sound patterns are subregular can be investigated, pointing the direction for future research. Taken together, these contributions show computational phonology is identifying stronger and stronger universal properties of phonological patterns, which are reflected in the grammatical formalisms phonologists employ. This article is intended primarily for phonologists who are curious about computational phonology, but do not have a rigorous background in mathematics or computation. However, it is also informative for readers with a background in computation and the basics of phonology, and who are curious about what computational analysis offers phonological theory.

1. Introduction

In Computational Phonology – Part I: Foundations, the foundations of the theory of computation were presented and the first major result of computational analysis of phonological patterns was given: they are regular patterns. This article explains why

1. different grammatical formalisms in phonology [in particular, ordered rewrite-rule phonology (SPE), Two-Level Phonology (2LP), Declarative Phonology (DP), and Optimality Theory (OT)] are similar to each other from a computational perspective,
2. computational analysis informs stochastic approaches to grammars,
3. computational analysis is of paramount importance in addressing the learning problem, and
4. why the future of computational analysis of phonological patterns is subregular.

Part I emphasized that phonological theories factor the phonology of a language into individual generalizations as shown in Figure 1. It was explained that for SPE-style grammars, Kaplan and Kay (1994) showed that each rule \( F_i \) encodes a regular relation and that the interaction of these rules \( \times \) is exactly given by the composition operation \( \circ \) of finite-state transducers. Assuming that phonological rules cannot re-apply to the locus of their structural change, it follows that the phonology of the whole language \( P_L \) is also a regular relation, describable with a single finite-state transducer.

\[
F_1 \times F_2 \times \ldots F_n = P_L
\]
In this article, Sections 2–4 show that research on 2LP, DP, and OT reveals that the grammars in these theories also describe generalizations and whole phonologies as regular relations, which interact in similar ways. Sections 5–7 discuss stochastic grammars, learning, and subregular properties, respectively. Section 8 concludes.

2. Two-level Phonology

2.1. Architecture

Inspired by Kaplan and Kay (1981), Koskenniemi (1983) presents a theory of phonology called two-level phonology (2LP). Under this theory, all individual phonological generalizations ($F_i$) are stipulated to be regular relations, but these relations are no longer conceived as rules that transform one string to another. Rather, they are individual constraints that enforce well-formedness conditions on alternations in parallel. These conceptual shifts ought not be underestimated as they foreshadow the later development of OT (Prince and Smolensky 2004).

The interaction of these constraints is accomplished through what I will call the path product operation on finite-state transducers. Examples of paths are given in Part I. Every transducer not only describes a regular relation, it also describes a set of paths. The path product of $T_1$ and $T_2$ is an operation that yields another transducer which describes exactly the intersection of the paths of $T_1$ and $T_2$. Kaplan and Kay (1994) explain this operation in more detail.

Karttunen (1993) makes clear that the 2LP grammars decompose the phonology of the whole language in a different manner than the way SPE grammars do. The decomposition in 2LP is just as logically consistent as the one in SPE. Both state individual phonological generalizations as regular relations. 2LP uses path product, but SPE uses composition.

2.2. Expressivity

Kaplan and Kay (1994) apply their analysis to 2LP and show that it, like the SPE-style grammars, expresses all and only regular relations. They conclude ‘Although there may be aesthetic or explanatory differences between the two formal systems, empirical coverage by itself cannot be used to choose between them’.

2.3. Computational Complexity

Barton et al. (1987) determine the generation problem (part I, problem 4-a) for 2LP grammars is only solvable in non-deterministic polynomial time (NP), when the grammars are given as a set of individual generalizations. In other words, there is no deterministic algorithm that is guaranteed to compute the surface form from any underlying form for any 2LP grammar in fewer than $f(n)$ steps where $f$ is a polynomial function and $n$ is the length of the underlying form. This is due to the fact that taking the path product of arbitrarily many finite-state machines (FSMs) belongs to NP (Hopcroft et al. 2001).

Barton et al. (1987) make clear that complexity results of this kind ought to lead to future work. Complexity results necessarily consider the worst case, but whether actual phonologies are among the worst cases remains unknown. Given the earlier observation that phonological patterns are almost certainly subregular, it is a distinct possibility that actual phonologies are not among the worst cases, but instead belong to less expressive, but more computationally tractable, areas of the regular languages.
3. Declarative Phonology

3.1. ARCHITECTURE

Declarative Phonology (Coleman 2005; Scobbie 1993), like 2LP, maintains that each phonological generalization \((F_i)\) is an exceptionless constraint expressed as a regular relation and every constraint must be satisfied by every form. But the interaction of these relations is via set intersection \((\cap)\). Consequently, the whole phonology maps an underlying form \(u\) to a surface form \(s\) if and only if every individual phonological generalization maps \(u\) to \(s\). In FSM terms, set intersection \((\cap)\) is equivalent to the automata product \((\times)\) operation, which is distinct from the path product.

One difference between DP and 2LP is that a lexical item is explicitly given as a finite language which contain all and only its surface variants. For example, consider a prefix which ends with a nasal, which always agree in place with the following consonant (and assume there are no vowel-initial words). As it is impossible to ascertain the place of the nasal, the prefix is represented as a finite-state acceptor which describes the language \(\{im-, in-, i\eta-\}\). This is similar to underspecification analyses in phonology (Archangeli 1988; Ito et al. 1995; Mohanan 1991; Steriade 1995; see also Hooper 1976).

Another difference between DP and other theories is that the individual generalizations were stated with logical formulae because DP’s proponents wanted to emphasize the denotational nature of phonological constraints with declarative statements, independent of any particular implementation.

3.2. EXPRESSIVITY

Regular relations are not closed under intersection. This means that the intersection of two regular relations may not be regular.\(^2\) Thus, even though DP presumes the constraints are regular, there is nothing in the theory that ensures that the phonology of the whole language \((P_L)\) is regular. Thus, DP is strictly more expressive than either SPE or 2LP and consequently, as a scientific hypothesis about what is a possible phonological pattern, is a weaker theory than either SPE or 2LP. As far as I know, this additional expressivity is also unnecessary as no bonafide context-free phonological pattern has been established.

3.3. COMPUTATIONAL COMPLEXITY

Computing the product of arbitrarily many FSMs belongs to NP (Hopcroft et al. 2001). Consequently, as with 2LP, it remains to be learned whether further restrictions on possibles constraints in DP alleviates this intractability.

4. Optimality-Theoretic Phonology

4.1. ARCHITECTURE

SPE, 2LP, and DP view the individual phonological generalizations \((F_i\) in Figure 1) as language-specific. On the other hand, in OT every language has the same individual phonological generalizations (McCarthy and Prince 1995; Prince and Smolensky 1993, 2004), and languages only differ in how those generalizations interact. Like DP and 2LP, the individual generalizations are constraints. But the interaction \((\times)\) of constraints in OT
is more subtle than in either of those theories: the constraints are prioritized and underlying forms are mapped to surface forms which optimally satisfy these constraints. Standardly, constraints are stipulated to come in two kinds: **Markedness Constraints**, which penalize alternations with marked surface forms, and **Faithfulness Constraints**, which penalize surface forms which deviate from the underlying form (Kager 1999; McCarthy 2007b; Prince and Smolensky 2004).

Formally, the architecture of OT grammars admits three main components. **Gen** relates underlying forms to a potentially infinite set of candidate surface forms. **Con** is a list of totally ordered constraints, each of which maps an underlying form \( u \) and a candidate surface form \( s \) to a non-negative integer (the number of times \((u, s)\) violates the constraint). Thus, as a whole, **Con** maps each \((u, s)\) pair to a vector of numbers called the violation profile. **Eval** selects, for a given underlying form, the candidate surface form with the most favorable violation profile: the one that violates the most important constraints the least.

Prince (2002) establishes the logic of constraint interaction and procedures for reasoning about OT grammars from the essential information provided by violation profiles. This work makes clear the logical foundation for the inference of constraint ranking from partial information originally explored by Tesar (1995), which is discussed in more detail below.

### 4.2. Expressivity

How restrictive is the theory? In a departure from 2LP and DP, the founders of OT made no assumption that it ought to ‘be regular’. As Eisner (1997b) observes, without restricting what counts as a possible markedness or faithful constraints, there are hardly any limits on the expressivity of OT. For example, it is generally assumed that a context-free markedness constraint which assigns violations to words with a string of \( n \) consonants followed by \( n \) vowels (\( C^n V^n \)) does not belong to the **Con**, but nothing in the theory precludes this.

Such constraints are probably tacitly omitted because of the intuitions phonologists have that no phonology permits such an individual phonological generalization. Indeed, much phonological research examines the expressivity of OT grammars by comparing predicted typological facts to known typological facts. Idsardi (1998, 2000) and Bakovic (2007) establish that OT is unable to describe some attested opaque alternations. Other research establishes that the interaction of plausible constraints either neatly matches the relevant typology (Kager 1999; McCarthy and Prince 1995; Prince and Smolensky 1993) or leads to undesirable typological predictions due to the unexpected ways constraints interact (Eisner 1997a,b; Gordon 2007; McCarthy 2003; Wilson 2001). Antilla (2008) describes a procedure which calculates a *typological order* from a given set of candidates with their violation profiles, which provides another way to measure the predictions a set of constraints makes against the known typology.

Given earlier results that showed phonological patterns are regular, other researchers have asked what conditions need to be placed on **con** and **gen** to ensure that an OT grammar describes a regular relation. Frank and Satta (1998) show that if the only requirements are that **gen** and the contents of **con** be regular then OT grammars can describe context-free relations. Placing an upper bound on the number of violations regular constraints in **con** can assign, however, reduces the expressivity of OT grammars to regular relations. Like Kaplan and Kay’s work, their proof is constructive. Karttunen (1998) achieves the same conclusion constructively and further expresses the interaction...
of the constraints precisely in terms of an operation called lenient composition (because it is defined in terms of ordinary composition and a special union operation over relations). Together these researchers show that, under the assumptions stated above, that OT grammars combine regular OT constraints in a manner which describes a single regular relation. The importance of this result is that differences between OT grammars and SPE-style rule grammars fade away: like 2LP and DP, they are both particular compositions of regular relations which ultimately describe the same regular, functional characterizations of phonological patterns. This point is made repeatedly by Karttunen (1993, 1998).

Another question is whether every regular relation can be expressed with an OT grammar. This question has not been answered. I venture that, unlike Kaplan and Kay’s (1994) work, it is not the case that any regular relation can be described by an OT grammar, at least with traditional (and regular) markedness and faithfulness constraints. This is because there are regular relations which describe opaque alternations (because they are describable with SPE-style phonologies), which cannot be described by OT grammars (McCarthy 2007a).

4.3. THE GENERATION PROBLEM

Ellison (1994) was the first to give a solution to the generation problem (Part I, 4-a) in OT. Frank and Satta (1998) provide a simpler solution, and Karttunen’s (1998) lenient composition operator makes their solution clearer. Gerdemann and van Noord (2000) improve Karttunen’s result in the sense that they obtain a more efficient implementation.

Riggle’s (2004) constructive, computational analysis of OT is especially noteworthy because he shows that the generation problem in OT can be solved using Dijkstra’s shortest paths algorithm (Dijkstra 1959). Riggle presents a ranking-independent representation of Eval as a finite-state transducer where the transitions are ‘weighted’ with violation profiles. This FSM is constructed through a special product operation over the constraints in Con (represented as transducers) called M-intersection. Given the ranking of constraints and this representation, Dijkstra’s algorithm finds the optimal path through the machine in linear time. Furthermore, unlike earlier approaches, there is no need to place an upper bound on the number of violations constraints can assign to achieve this result.

Riggle also shows how to efficiently generate the contenders – all and only those candidates that could win under any possible ranking, which provides a solution to the typological problem (Part I, 4-d). Even though Riggle’s Gen produces infinitely many candidates, in a variety of simulations, the contenders are few.

Recalling Frank and Satta’s results, an open question remains: Is the particular Gen function which Riggle employs one that permits the construction of a regular transducer for any (regular) Con and ranking? More generally, what restrictions are necessary on Eval, Gen, or Con to guarantee that optimization yields a regular relation? Riggle (2004) presents some preliminary, promising work addressing this issue.

4.4. COMPUTATIONAL COMPLEXITY

Eisner (1997a, 2000) building on work by Ellison (1994), was the first to establish that the generation problem in OT is NP as the number of tiers or constraints grows arbitrarily large. Wareham (1998) proves the same result with a different proof and Idsardi (2006) presents an alternative version of Eisner’s proof using phonologically standard constraints. Heinz et al. (2009) qualify their results by identifying the source of hardness to be computing the
product of individual constraints. (Recall that the automata product of individual FSMs, which represent constraints, belongs to NP.) If the constraint set is represented differently [with Riggle’s (2004) ranking-independent EVAL] then, as mentioned, the generation problem becomes linear. But if EVAL is represented in terms of individual constraints then their compilation into a ranking-independent EVAL with M-intersection is also NP.

4.5. OT VARIANTS

There are many distinct variants of OT; three are discussed here. The original version (Prince and Smolensky 1993), dubbed containment theory, requires that all candidates produced by GEN to be at least as long as the underlying form, with special markers indicating deletions and epenthesis. With the exception of Riggle (2004), it is this version that has been subject to the computational analyses above.

McCarthy and Prince (1995) introduce correspondence theory where underlying forms are indexed and GEN produces every logical possible indexing over every logically possible word. Thus, the underlying form /k1æ2t3/ has fully merged candidates [k1,2,3], partially merged candidates [k1,2], ‘reverse’ candidates like [k3æ2t1] and [t3æ2k1], epenthetic candidates [k1æ2t3s], split candidates [k1æ2t3s1], and so on.

McCarthy (2008) presents harmonic serialism (HS), where GEN is very restricted. Informally, for each underlying form, the candidates produced by GEN can differ by at most one single change, where a single change is roughly speaking, a single insertion, deletion, or substitution. If this was all there was to it, then HS would be inadequately expressive since many phonological alternations exhibit several changes between underlying forms and their surface forms. However, HS asserts that EVAL and GEN are called repeatedly: for an underlying form u, EVAL selects the best candidate c1 from Gen(u), and then EVAL selects the best candidate c2 from Gen(c1) and so on until candidate cn+1 = cn. In this way, HS is a model which is both derivational and constraint-based. Taking what is meant by ‘single change’ at face value, it appears this GEN is regular, which would suggest that the kinds of relations HS describes are subject to the results of Frank and Satta’s, Karttunen’s, and Riggle’s analyses.

4.6. SUMMARY

Table 1 summarizes the architectures of the different formalisms and some of the known and unknown facts. Because finite-state transducers, which can describe all and only the regular relations, are solutions to both the generation and recognition problems (Part I, 4-ab), the theories which necessarily describe the whole phonology as a regular relation, have solutions to both of these problems.

5. Stochastic Phonology

Recall the optional rule of word-final coronal stop deletion in English from Part I, repeated below.

(1) [+coronal, −continuant] → θ/C______#

Functional characterizations of phonological generalizations with a codomain of {0,1} as shown in Part I are unable to distinguish the frequency with which the rule applies, and are unable to make finer distinctions in the grammaticality or acceptability of possible surface variants.
For these reasons, sociolinguists and phonologists make use of stochastic grammars, which not only describe functional characterizations with real codomains, but also leverage results from statistics and probability theory. Although it may be surprising, it is nevertheless true: changing the codomain of the functional characterizations from \( \{0, 1\} \) to the set of real numbers in this way does not change their expressivity. A regular language which is made stochastic is still regular (Vidal et al. 2005a,b). In fact, every region of the Chomsky Hierarchy admits a probabilistic counterpart (Booth 1969; Charniak 1996). Thus, although in some sense probabilistic grammars allow finer distinctions to be made, in an important sense they are fundamentally the same as their non-probabilistic counterparts. This is because formal language theory determines expressivity based on structural properties of grammars, which are independent of whether the codomain of the functional characterization of the language they describe is real or boolean.

### 5.1. FREE VARIATION

Within SPE-style grammars, each rule can be assigned a probability. The optional rule in (1) can be given as follows.

(2) \([+\text{coronal}, -\text{continuant}] \rightarrow \emptyset/C\ldots\# \quad (0.3)\)

This means at the stage of the derivation when the rule could apply, it applies 30% of the time (Guy 1980; Sankoff 1978; Sankoff and Labov 1979). In terms of the functional characterization of this generalization, pairs of forms are mapped to real values. A fragment of the generalization stated in (2) is shown in Figure 2. Anttila (1997) and Boersma (1997) provide different approaches to free variation within OT.

### 5.2. GRADIENT ACCEPTABILITY JUDGEMENTS

Phonologists also employ probabilistic grammars to predict gradient acceptability judgements humans give to novel word forms under laboratory conditions. Although

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Table 1. The architectures of different phonological theories expressing how different factors (i.e., phonological generalizations) interact to describe the phonology of a language, recalling that \( F_1 \times F_2 \times \cdots \times F_n = P_L \). OT-CT and OT-R04 are the containment theory and Riggle’s (2004) variants, respectively.

<table>
<thead>
<tr>
<th>( F_i )</th>
<th>Other conditions</th>
<th>Properties of ( P_L )</th>
</tr>
</thead>
<tbody>
<tr>
<td>SPE</td>
<td>Regular, lg. specific Composition Rules cannot re-apply to locus of structural change</td>
<td>Is regular, Is regular</td>
</tr>
<tr>
<td>2LP</td>
<td>Regular, lg. specific Path product None</td>
<td>Is regular, Is regular</td>
</tr>
<tr>
<td>DP</td>
<td>Regular, lg. specific Intersection None</td>
<td>Is context-free, Unknown</td>
</tr>
<tr>
<td>OT-CT</td>
<td>Regular, universal Lenient composition None</td>
<td>Is context-free, Unknown</td>
</tr>
<tr>
<td>OT-R04</td>
<td>Regular, universal M-intersection None</td>
<td>Unknown, Unknown</td>
</tr>
</tbody>
</table>

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well-formedness and likelihood are logically distinct notions, this research makes the strong hypothesis that they are in fact the same (Albright 2009; Albright and Hayes 2003; Antilla 2008; Coetzee 2008; Coetzee and Pater 2007; Coleman and Pierrehumbert 1997; Frisch et al. 2004; Hayes and Wilson 2008; Heinz and Koirala 2010; Heinz and Rogers 2010; Pater 2009).

6. Learning Phonology

There are different characterizations of the learning problem (Anthony and Biggs 1992; Gold 1967; de la Higuera 2010; Jain et al. 1999; Vapnik 1998). Learners, however, are always characterized as functions which map data to grammars. Furthermore, learners are always evaluated in terms of the class of concepts (i.e. languages, relations, stochastic languages, etc.) they are guaranteed to learn under defined criteria of what it means to ‘learn’. This makes sense from the computational perspective discussed in Part I. From the computational perspective, learning algorithms are not just step-by-step procedures, they are step-by-step procedures that solve well-articulated problems. For learning algorithms proposed within phonology, we ought to ask What problem does this algorithm solve?

Recursive Constraint Demotion (RCD) is an algorithm in exactly this sense. Essentially, RCD solves the alternation learning problem (Part I, 4-e). Consider any finite set of computable constraints $\text{CON}$. Let a data point be an underlying form paired with its surface form and consider any finite set of data points. Question: What rankings of $\text{CON}$ (if any) are consistent with the set of data points? RCD provably answers this question correctly in every case (Tesar 1995; Tesar and Smolensky 1998, 2000).³

On the other hand, some of the proposed variants of RCD (Hayes 2004; Prince and Tesar 2004; Tesar 1999) are not algorithms in this sense. They are clear step-by-step procedures, but it is not known what problem they solve, in the computational sense of the word. Instead these variants are motivated in response to claims that RCD is inadequate in certain respects, and simulations are run in order to get a sense of whether the proposed variant appears to resolve this inadequacy. Often the simulation leads to observations that in some cases the inadequacy is resolved, but in others it is not. The next step in this process is to characterize these cases, and then to modify the variant further. If the simulations appear to work in every case, then it may be possible to state and prove which problem the variant is actually solving.

In my opinion, the simulation-based methodology is not the best way to develop an algorithm which provably solves a particular problem (RCD being a case-in-point). This

\[
\begin{align*}
  f & \quad \rightarrow 0.7 \\
  (\text{west,west}) & \quad \rightarrow 0.3 \\
  (\text{west,we}) & \quad \rightarrow 0 \\
  \cdots & \quad \\
  (\text{piwest,piwest}) & \quad \rightarrow 0.7 \\
  (\text{piwest,piwe}) & \quad \rightarrow 0.3 \\
  (\text{piwest,piwe}) & \quad \rightarrow 0 \\
  \cdots & 
\end{align*}
\]

Fig 2. Fragments of the functional characterization of the post-consonantal, word-final coronal stop deletion rule which applied 30% of the time.
is not to say that simulation-based research is not addressing real inadequacies with existing algorithms or that the ideas present in such procedures fail to capture important intuitions. However, I would argue that there is no replacement for a procedure which provably solves a problem. Knowing what problem the algorithm solves means intimately understanding the algorithm’s behavior. In this case, running the algorithm is no longer a simulation; it is a demonstration. In the growing field of modeling the acquisition of sound patterns, it is not a reach to say that simulations are the norm, and demonstrations are a rarity. One only need to witness the role RCD played in the development of OT to understand the power of procedures that are provable solutions to problems.

An instructive example of simulation-based research is from Gildea and Jurafsky (1996). They begin with OSTIA (Ocina et al. 1993), an algorithm that provably solves a problem: this algorithm identifies in the limit from positive data (Gold 1967) a proper subclass of regular relations, those that are describable by a subsequential transducer. Even though Gildea and Jurafsky show that the SPE-style English tapping rule can be represented by a subsequential transducer, they show that OSTIA fails to learn the rule, even when presented with a corpus of ~50,000 pairs of underlying forms and surface forms adapted from the Carnegie Mellon University (CMU) Pronouncing Dictionary, which were uniformly modified to exemplify the rule where it applied. They next modify OSTIA in three ways to capture the intuitions that similar sounds behave similarly, that underlying sounds are similar to the sounds they surface as, and that structural descriptions of rules may contain variables. They show that this modified OSTIA returns a transducer which much more closely represent the English tapping rule than what was returned by the original OSTIA algorithm.4

There are three important questions this work leaves us with, which have never been answered satisfactorily. First, why does OSTIA fail to learn the tapping rule? Gildea and Jurafsky hint at the answer: the kind of data that OSTIA would need to see to converge to the tapping rule is not present in the CMU dictionary. Importantly, it is not an issue of quantity, it is an issue of kind: OSTIA likely needs to see forms that would never occur in any English lexicon; for example, words with three adjacent [t]s. The second and third questions are: What class of rules can the modified OSTIA learn (i.e. What is the problem this algorithm solves?) and Why?

The answers to these questions are not yet known but tools exist to find them. It is often the case that algorithms which solve learning problems are able to characterize exactly the kind of data the algorithm needs to be fed in order for it to succeed. An early example comes from Angluin (1982). The grammatical inference community has provided many more such results (de la Higuera 2005, 2010). Examples relevant to phonology include Heinz (2010a,b). The utility of such characterizations are many. They can be used to develop artificial language experiments and they can be compared with the forms to which children and infants are actually exposed. In the case of OSTIA above, it ought to be possible to identify the kind of data OSTIA needs to learn the English tapping rule and whether such data is present in the CMU dictionary (all without actually running the learning algorithm!)

Additional influential work which approaches phonological learning with simulations include Coleman and Pierrehumbert (1997), Ellison (1992), Boersma and Hayes (2001), Albright and Hayes (2003), Hayes and Wilson (2008), Albright (2009), Goldsmith and Xanthos (2009), Tesar (forthcoming), Heinz (2009) and Goldsmith and Riggle (forthcoming). Apart from RCD, work within phonology which presents algorithms which provably solve learning problems include Riggle (2009), Magri (2009), Heinz (2010a,b), and Heinz and Rogers (2010). Magri (2010) also proves that the phonotactic learning
problem (Part I, problem 4-d) within OT is not in P. Notably, he suggests research ‘to find phonologically plausible assumptions on generating function and constraint set that make the problem of the acquisition of phonotactics tractable’.

7. Subregular patterns

Recall the hypothesis presented in Part I that phonology is subregular, restated below:

(3) Hypothesis: Phonology ⊂ Regular

There are three reasons to be interested in subregular language classes.

First, although any phonological pattern is regular, ‘being regular’ does not make a pattern a possible phonological one. This is because there are many regular patterns which are not phonological (for example, patterns that require words to have a number of consonants evenly divisible by some \( n \)). Classifying phonological patterns according to known subregular language classes helps us understand what kind of regular patterns they are. In turn, this allows strong, restrictive hypotheses of universal properties of phonological patterns to be formulated and examined.

Second, several negative complexity results mentioned above follow when a parameter of the problem includes all regular patterns. Virtually every researcher acknowledges that if stronger, assumptions are made, these negative results may disappear. It is perfectly possible – but unknown – whether restricting the parameters of problems to certain subregular classes eases the problems’ complexity.

Third, there is wide consensus that the learning problem is hampered by hypothesis spaces that are too expressive (Gallistel and King 2009; Jain et al. 1999; Sober 2008; Vapnik 1998). If the right restrictive properties are discovered, it is possible that they may contribute to the learnability of phonological patterns (Heinz 2007, 2009, 2010a; Magri 2010; Tesar forthcoming).

7.1. SUBREGULAR HIERarchIES

The class of regular languages contains a dual hierarchy of nested regions. There is a local branch and a piecewise branch. Figure 3 shows the proper inclusion relationships in this hierarchy. Rogers and Pullum (forthcoming) and Rogers and Hauser (2010) provide an accessible introduction to the local branch and Rogers et al. (2010) to the piecewise branch. The local branch was originally studied by McNaughton and Papert (1971) and the piecewise languages by Simon (1975) and Rogers et al. (2010).

Each language class in these hierarchies has independently motivated, converging characterizations and is claimed to correspond to specific, fundamental cognitive capabilities (Rogers and Hauser 2010; Rogers and Pullum forthcoming). Here, I provide an informal treatment.

Languages along the local branch only make distinctions on the basis of contiguous sub-sequences (up to some length \( k \), known as \( k \)-factors). For example, the \( 2 \)-factors of \( \times abcd \times \) are \( \{ \times a, ab, bc, cd, d \times \} \) (\( \times \) and \( \times \) are the left and right word boundaries, respectively). Grammars of strictly \( k \)-local (\( SL_k \)) languages can be thought of as sets of prohibited \( k \)-factors and the words belonging to the language of the grammar are all and only those words which do not contain any of those \( k \)-factors. For example, the grammar \( \{ ab \} \) generates the language that contains all words with no contiguous \( ab \) sequence. Grammars of
Locally K-Testable (LT<sub>k</sub>) languages can be thought of as sets of sets of prohibited <i>k</i>-factors and the words belonging to the language of the grammar are those words whose set of <i>k</i>-factors is not the same as any of the prohibited sets in the grammar. For example, the LT<sub>2</sub> grammar \{\{\times a, ab, bc, c\times\}\} generates the language that contains all words except those with exactly the 2-factors \times a, ab, bc, and c\times, i.e., all words but abc (so abcd is part of the language).

Languages along the piecewise branch only make distinctions on the basis of subsequences (up to some length \(k\), not necessarily contiguous). For example, the two-long subsequences of abcd are \{ab, ac, ad, bc, bd, cd\}. Strictly K-Piecewise and Piecewise K-Testable grammars and languages are defined analogously to (SL<sub>k</sub>) and (LT<sub>k</sub>) grammars and languages, respectively.

Finally, the Noncounting class of languages includes all and only those regular patterns which do not count modulo some number \(n\) (so it excludes constraints that penalize words with an even number of consonants, for example). McNaughton and Papert (1971) show that for every noncounting language, there is some \(n\) such that for all logically possible words \(u,v,w\), either both \(uvw^n w\) and \(uvw^{n+1} w\) belong to the language or neither do.

### 7.2. What Kinds of Subregular Patterns Are Actual Phonologies?

Recent work has begun to address where phonological patterns fall in the Subregular hierarchy. A first hypothesis is that markedness constraints are Strictly Local. For example, Hayes and Wilson (2008) use this kind of constraint exclusively, and many markedness constraints in OT appear to belong to SL (though no comprehensive survey has been conducted). Locally conjoined markedness constraints (Smolensky 2006) like *ab&*bc are Locally Testable when the domain is the word. Heinz (2010a) hypothesizes that long-distance phonotactic constraints are Strictly 2-Piecewise. Edlefsen et al. (2008) examine whether stress patterns are Strictly Local and if so for what \(k\). They find \(\sim 72\%\) are SL<sub>k</sub> for \(k\leq 6\) and that \(\sim 49\%\) are SL<sub>k</sub> for \(k\leq 3\). Graf (2010) shows that some stress patterns are not Noncounting.
There are other subregular classes of languages. Heinz (2007, 2009) hypothesizes that all stress patterns and all phonotactic patterns are NEIGHBORHOOD–DISTINCT, an automata-theoretic locality condition, which defines a class which cross-cuts the subregular hierarchies. Heinz (2007) shows that the neighborhood-distinct languages properly includes the SL$_3$ and SP$_2$ language classes. No language-theoretic characterization of the neighborhood-distinct class yet exists, though Heinz (2008) begins the analysis.

Tesar (forthcoming) hypothesizes that phonological patterns are output-driven. It is not known whether all regular relations can be defined in terms of output-driven maps. I conjecture output-driven regular relations are subregular; i.e. there is at least one regular relation which is not output-driven.

### 7.3. SUBREGULAR RELATIONS

As currently defined, the subregular classes are languages (functions with domain $\Sigma^*$) suitable for describing phonotactics and/or markedness constraints, and not relations (functions with domain $\Sigma^* \times \Sigma^*$), which are suitable for describing alternations. It is an open question how to most fruitfully generalize the subregular hierarchies from sets to relations.

### 8. Conclusions

The computational study of phonology makes clear that the similarities between competing phonological theories outweigh their differences. In each case, the grammar formalisms decompose the phonology of a language $P_L$ into individual generalizations, which interact in particular ways. Although the nature of the generalizations and interactions differ in the frameworks, they all have something very important in common: the individual generalizations can all be described as regular relations, their interaction can all be described as a kind of product over regular grammars, and attested phonologies (the $P_L$ themselves) can be described as regular relations.

Current computational analysis of phonological patterns is revealing stronger, universal properties of phonological patterns. They are subregular. A current hypothesis locates the individual generalizations in the Strictly Local and Strictly Piecewise classes (and their yet-to-be-determined relational counterparts). Stress patterns appear more complex.

It is my hope that this article communicates the importance of the computational perspective to the study of phonology, and more generally to linguistic theory. Several open problems have been identified, which, along with the computational perspective, I hope encourages people to undertake computational analysis when studying the sound patterns in the world’s languages.

### Short Biography

Jeffrey Heinz’s research is located at the intersection of theoretical linguistics (specifically phonology), theoretical computer science, computational linguistics, grammatical inference, and cognitive science. He has authored or co-authored articles in these areas for the journals *Phonology, Linguistic Inquiry,* and the *Journal of Child Language*; chapters in the forthcoming Blackwell Companion to Phonology and Cambridge Handbook of Developmental Linguistics; and papers in the Proceedings of the annual meeting of the Association for Computational Linguistics and of the International Colloquium on Grammatical Inference. His current research centers on the hypotheses that phonology is subregular.
and that phonological learning is modular. He holds a BS in Mathematics and a BA in Linguistics from the University of Maryland, College Park, and a PhD in Linguistics from the University of California, Los Angeles. Jeffrey Heinz is currently an Assistant Professor at the University of Delaware.

Notes
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1 Koskenniemi called his theory ‘Two-Level Morphology’ since he describes morphophonological alternations.
3 Boersma (2009) has shown that RCD’s pooling violations of candidates can result in a stratified hierarchy of which some linearizations do not select the right candidate. Boersma’s alternative is to randomly select a linearization consistent with the stratified hierarchy and he shows this converges in the sense Tesar and Smolensky intended.
4 They also study the case of German word-final stop devoicing.
5 Technically, we let all logically possible words belong to \( \{ \times \} \Sigma^* \{ \times \} \).
6 Unlike with the Local branch, word boundaries are unnecessary here.
7 The Locally Testable grammar would include all subsets of \( \Sigma^2 \) that have both \( ab \) and \( bc \). If the domain is smaller than the word then the pattern is Strictly \( k \)-Local iff the size of the domain is bounded by \( k \). Otherwise, the pattern belongs to some to-be-determined subregular class.
8 Others that have been studied for their learnability properties include Angluin (1982) and Heinz (2008, 2010b).

Works Cited
Coetzee, Andries, and Joe Pater. 2007. Weighted constraints and gradient phonotactics in Muna and Arabic. Amherst: University of Michigan and University of Massachusetts.


